

Checkmk Synthetic Monitoring

Community Call

2024, April 30



Simon Meggle PM Synthetic Monitoring Checkmk GmbH checkmk.com

About me Simon Meggle

- 2000-2011: IT administrator
- 2011-2018: Monitoring consultant, employed
- Since 2018: self-employed, founded **ELABIT GmbH**
- Since 2020: Robot Framework/Robotmk
 - O Robotmk Development
 - Robot workbench provider
 - O Workshops/Trainings
- Since 2022: Product Manager "Synthetic Monitoring", Checkmk GmbH







Introduction to Synthetic Monitoring

- Robot Framework
- 03 Robotmk
- **Demo**: Robotmk in Checkmk 2.3
- Synthetic Monitoring as a Checkmk product

06 Outlook



Introduction to Synthetic Monitoring



Synthetic Monitoring What does that mean? Synthetically mimic interactions of users with target systems 3 dimensions are relevant: Monitoring Availability: do the services respond? **Performance:** how is the response quality? Functionality: does the system provide the expected **OK** functionality?

 \bigcirc

 \bigcirc

 \bigcirc

```
1
 2
 3
 4
 5
 6
 9
10
11
12
13
14
15
16
17
```

from selenium import webdriver

driver = webdriver.Chrome(r'C:\Users\drivers\chromedriver.exe')
driver.maximize_window()
driver.get("http://www.seleniumeasy.com/test/basic-first-form-demo.html")
assert "Selenium Easy Demo - Simple Form to Automate using Selenium" in driver.title

eleUserMessage = driver.find_element_by_id("user-message")
eleUserMessage.clear()

```
eleUserMessage.send_keys("Test Python")
```

eleShowMsgBtn=driver.find_element_by_css_selector('#get-input > .btn')
eleShowMsgBtn.click()

eleYourMsg=driver.find_element_by_id("display")
assert "Test Python" in eleYourMsg.text
driver.close()



- Generic test automation framework
- Python, Open Source
- Key features:
 - O library concept
 - O keyword driven approach
- Outstanding:
 - Community
 - Foundation



Robocon

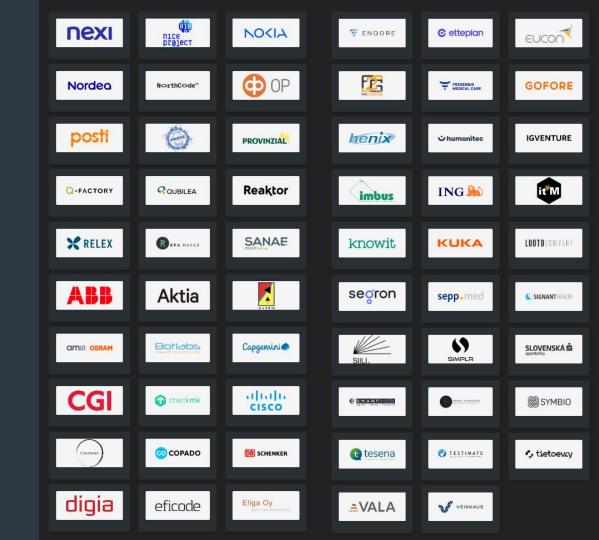
- Yearly conference in Helsinki, Fl
- Workshop day
- Open Space day
- 2 conference days





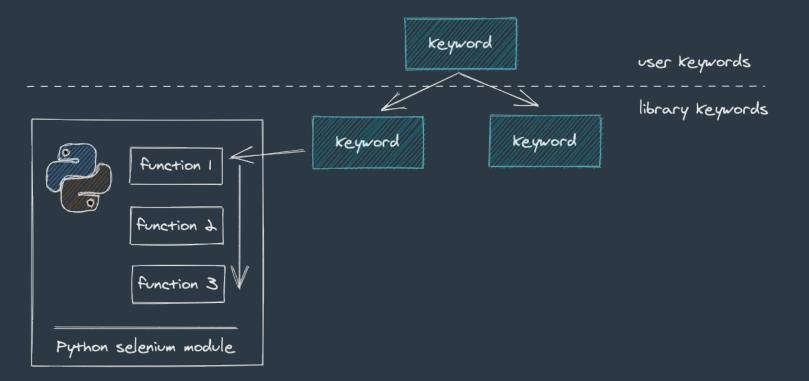
Foundation

- > 60 companies
- Pay developers
- Sponsors events
- Supports contributions
- Protects Robot Framework

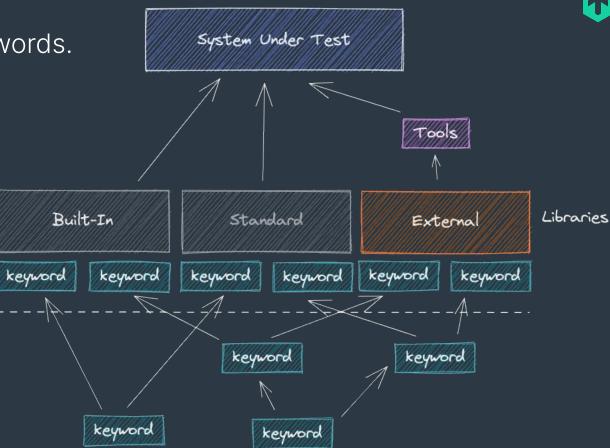


Robot Framework Keywords **encapsulate** Python code.





Robot Framework Libraries **organize** keywords.



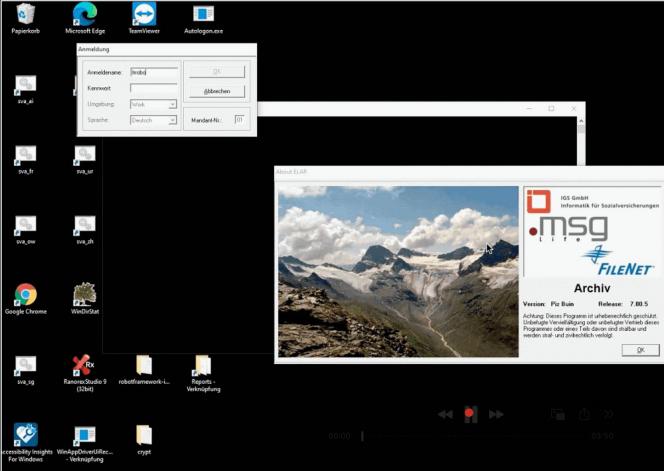
- Web automation (SeleniumLibrary, Playwright)
- Desktop/OS automation
- by Win32 API (FlaUI, Zoomba.Desktop, AutolT)
- by Image pattern recognition (ImageHorizonLibrary)
- Network (SSH, REST, SOAP, Telnet, ...)
- Kubernetes (KubernetesLibrary)
- PDF/Image comparison (DocTest library)
- CryptoLibrary (encrpyt sensitive data)
- many more...
- self-written libraries (Python functions become keywords)



ок	E2E VISUSTORE Calculation - CalcEngine	≡‴⊖≡	ОК - в [T] 'CalcEngine': PASS (last execution: 04/22 14:35:31) , runtime=3.86s
ок	E2E VISUSTORE Calculation - Close Order	≡≦0≣	OK - c [T] 'Close Order': PASS (last execution: 04/22 14:35:34)
ок	E2E VISUSTORE Calculation - Enter Order Data	≡ãΩ≣	OK - □ [T] 'Enter Order Data': PASS (last execution: 04/22 14:35:20)
ок	E2E VISUSTORE Calculation - Input FrameData	≡ã⊙≣	OK - □ [T] 'Input FrameData': PASS (last execution: 04/22 14:35:27)
ок	E2E VISUSTORE Calculation - Lens Type Selection	≡ã0≣ <mark>=</mark>	OK - □ [T] 'Lens Type Selection': PASS (last execution: 04/22 14:35:23) , runtime=3.25s
ок	E2E VISUSTORE Calculation - Login	≡∭0⊒=	OK - ¤ [T] 'Login': PASS (last execution: 04/22 14:35:16) , runtime=5.85s
ок	E2E VISUSTORE Calculation - LogOut	≡∭⊖∃=	OK - □ [T] 'LogOut': PASS (last execution: 04/22 14:35:39)
ок	E2E VISUSTORE Calculation - Open Order	≡∭0⊒=	OK - = [T] 'Open Order': PASS (last execution: 04/22 14:35:18) , runtime=2.76s
ок	E2E VISUSTORE Calculation - Order Review	≡∭C≣=	OK - c [T] 'Order Review': PASS (last execution: 04/22 14:35:32) , runtime=0.98s
ок	E2E VISUSTORE Calculation - Place Order	≡∭0 ⊒ =	OK - □ [T] 'Place Order': PASS (last execution: 04/22 14:35:34) , runtime=2.49s
ок	E2E VISUSTORE Calculation - Shape and Bevel	≡ã⊙≡=	OK - c [T] 'Shape and Bevel': PASS (last execution: 04/22 14:35:24)







"The decision for Robot Framework is NOT a decision for a software vendor.

It's the decision for the NGUA FRANCA of test automation."

The Robotmk project

Past and today



The Robotmk Project





The Robotmk Project

Past, today and the future

Past: one man show

- Prototype presented at Robocon 2020
- Good perception, first customer projects
- Checkmk integration was as good as it could, based on MKP
- Customer driven development
- Since mid 2022: Cooperation with Checkmk
 - Deeper integration
 - Code quality
 - Faster development
 - ✓ More features



Robotmk in Checkmk 2.3



Robotmk in Checkmk 2.3

Goals & Features

- Main Goal: deeper integration with the features of V1
- Complete rewrite (Rust)
- Focus on Windows (main use case), Linux later
- Main Features:
 - O Robotmk Scheduler: individual execution intervals
 - O Integration of RCC: individual Python environments

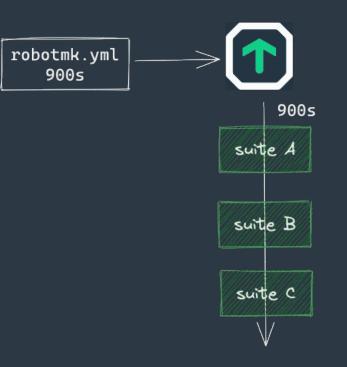
⇒ **DEMO**: Integration of a web based test into Checkmk





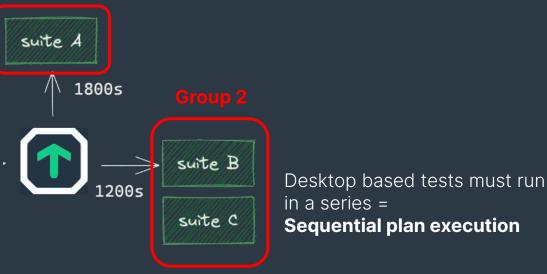
Robotmk in Checkmk 2.3 Execution: Robotmk v1





Robotmk in Checkmk 2.3 Sequential & Parallel Plan Execution

Group 1



 \Rightarrow Robotmk Scheduler does not execute suites/plans, but execution groups!



Synthetic Monitoring as a Product in Checkmk 2.3



Synthetic Monitoring Product and pricing



- Already Included in Enterprise, Cloud (on prem) and MSP editions
- Free Tier: Test all features with up to 3 discovered test services
- > 3 tests:
 - Subscription required, includes support for Robotmk (not RF)
 - Starts with €150/month
 - Pricing highly depends on the use case ⇒ contact sales

Outlook



1

Outlook Planned Features

Most relevant:

- Integrated Robot Management
 - ⇒ upload RF suites into Checkmk, deploy via bakery

Improved keyword monitoring

- ⇒ make metrics more robust against renamings
- \Rightarrow KPI monitoring: Discover the states of SLA relevant keywords

• More insights into Synthetic Monitoring Data

- \Rightarrow more Dashboards & Views
- \Rightarrow Support RF Metadata for custom visualizations
- \Rightarrow add HTML to into Notifications



$\mathbf{\hat{v}}$

THANK YOU!

Robot Framework: https://robotframework.org

Repository: https://github.com/elabit/robotmk

Robotmk Blog: https://blog.robotmk.org

Checkmk Documentation: https://docs.checkmk.com/latest/de/robotmk.html



Simon Meggle PM Synthetic Monitoring Checkmk GmbH checkmk.com

